

NUC240 Driver GP2Y1010AU0F

NuMicro® 32 位系列微控制器範例代碼介紹

文件資訊

代碼簡述	本範例代碼為 NUC240 驅動 GP2Y1010AU0F 來計算 PM2.5 值。
BSP 版本	NUC230_240 Series BSP CMSIS v3.01.001
開發平台	NuTiny-SDK-NUC240V

The information described in this document is the exclusive intellectual property of Nuvoton Technology Corporation and shall not be reproduced without permission from Nuvoton.

Nuvoton is providing this document only for reference purposes of NuMicro microcontroller based system design. Nuvoton assumes no responsibility for errors or omissions.

All data and specifications are subject to change without notice.

For additional information or questions, please contact: Nuvoton Technology Corporation.

www.nuvoton.com

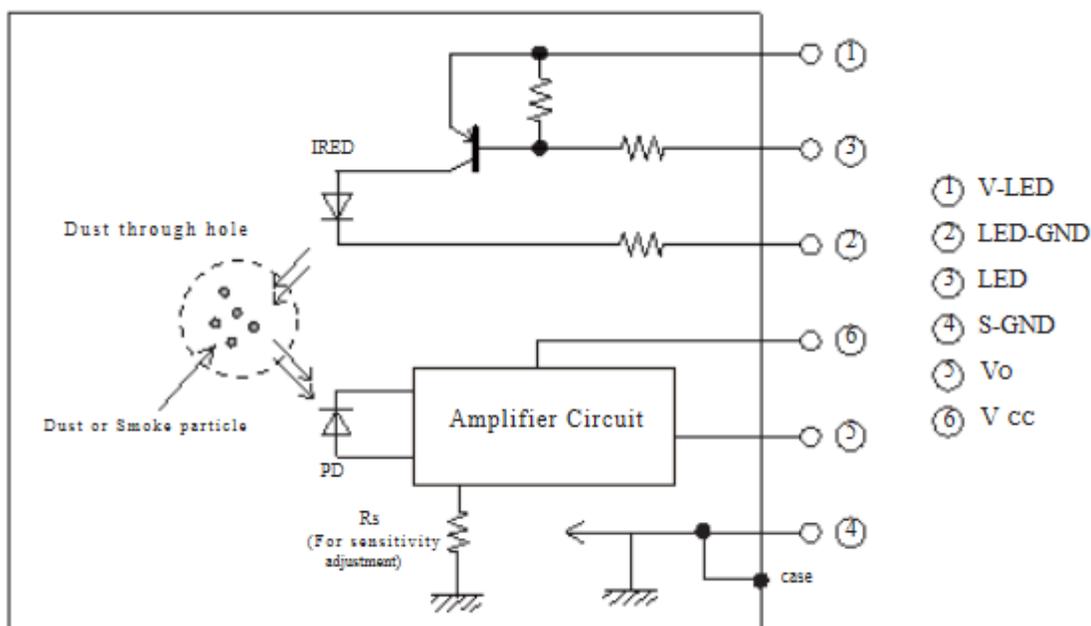
1 功能介紹

1.1 簡介

本範例代碼為 NUC240 系列通過 ADC 接口來讀取 GP2Y1010AU0F 的輸出 V_o 值，用於計算 PM2.5 數值。

1.2 原理

GP2Y1010AU0F 是一種由光學傳感系統構成的塵埃傳感器。一個紅外發光二極管 (IRED) 和一個光敏電阻器斜佈置在這個裝置。它能探測到空氣中灰塵的反射光。特別是對香菸煙霧等非常細小的顆粒的檢測是有效的。此外，它還可以通過輸出電壓的脈衝模式來區分煙霧和家居灰塵。



2 代碼介紹

計算 PM2.5 值:

```
void ADC_IRQHandler(void)
{
    g_u32AdcIntFlag = 1;
    ADC_CLR_INT_FLAG(ADC, ADC_ADF_INT); /* clear the A/D conversion flag */
}
int main(void)
{
    int32_t i32ConversionData;
    float calcVoltage, dustDensity;
    /* Unlock protected registers */
    SYS_UnlockReg();
    /* Enable ADC module clock */
    CLK_EnableModuleClock(ADC_MODULE);
    SystemCoreClockUpdate();

    /*ADC clock source is 22.1184MHz, set divider to 10, ADC clock is 22.1184/10 MHz */
    CLK_SetModuleClock(ADC_MODULE, CLK_CLKSEL1_ADC_S_HIRC, CLK_CLKDIV_ADC(11));

    /* Disable the GPA0 - GPA3 digital input path to avoid the leakage current. */
    GPIO_DISABLE_DIGITAL_PATH(PA, 0x1);

    /* Configure the GPA0 ADC analog input pins */
    SYS->GPA_MFP &= ~(SYS_GPA_MFP_PA0_Msk);
    SYS->GPA_MFP |= SYS_GPA_MFP_PA0_ADC0;
    SYS->ALT_MFP1 = 0;

    /* Set the ADC operation mode as single, input mode as single-end and enable the
    analog input channel 2 */
    ADC_Open(ADC, ADC_ADCR_DIFFEN_SINGLE_END, ADC_ADCR_ADMD_SINGLE, 0x1 << 0);

    /* Power on ADC module */
    ADC_POWER_ON(ADC);

    /* Clear the A/D interrupt flag for safe */
    ADC_CLR_INT_FLAG(ADC, ADC_ADF_INT);

    /* Enable the ADC interrupt */
```

```
ADC_EnableInt(ADC, ADC_ADF_INT);
NVIC_EnableIRQ(ADC_IRQn);

/* Configure PA.1 as Output mode*/
GPIO_SetMode(PA, BIT1, GPIO_PMD_OUTPUT);
LED_POWER_PIN = 1;

while (1)
{
    LED_POWER_PIN = 0; // power on the LED
    g_u32AdcIntFlag = 0;
    CLK_SysTickDelay(250); /* Reset the ADC interrupt indicator and Start A/D
conversion */
    ADC_START_CONV(ADC);
    CLK_SysTickDelay(3200); //delay 3.2ms

    /* Wait ADC interrupt (g_u32AdcIntFlag will be set at IRQ_Handler function)*/
    while (g_u32AdcIntFlag == 0);

    /* Get the conversion result of the ADC channel 0 */
    i32ConversionData = ADC_GET_CONVERSION_DATA(ADC, 0);
    LED_POWER_PIN = 1;
    // 0 - 5V mapped to 0 - 1023 integer values
    // recover voltage
    calcVoltage = (float)i32ConversionData * (5.0 / 1024.0);
    // linear equation taken from http://www.howmuchsnow.com/arduino/airquality/
    dustDensity = 0.17 * calcVoltage - 0.1;
    printf("Dust Density: ");
    printf("%.2f", dustDensity * 1000);
    printf(" ug/m3 \n\r");
    CLK_SysTickDelay(100000); //delay 100ms
}
}
```

參考資料:

<http://www.howmuchsnow.com/arduino/airquality/>

4 目錄資訊

EC_NUC240_ADC_GP2Y1010AU0F_PM2.5_V1.00

 Library	Sample code header and source files
 CMSIS	Cortex [®] Microcontroller Software Interface Standard (CMSIS) V4.5.0 definitions by ARM [®] Corp.
 Device	CMSIS compliant device header file
 StdDriver	All peripheral driver header and source files
 SampleCode	
 ExampleCode	Source file of example code

5 如何執行範例程式

1. 根據目錄資訊章節進入 ExampleCode 路徑中的 KEIL 文件夾，雙擊 NUC240_ADC_GP2Y1010AU0F_PM2.5.uvproj
2. 進入編譯模式
 - a. 編譯
 - b. 下載代碼到內存
 - c. 進入/離開仿真模式
3. 進入仿真模式接口
 - a. 執行代碼

6 修訂紀錄

Date	Revision	Description
Apr. 24, 2019	1.00	1. 初始發布.

Important Notice

Nuvoton Products are neither intended nor warranted for usage in systems or equipment, any malfunction or failure of which may cause loss of human life, bodily injury or severe property damage. Such applications are deemed, "Insecure Usage".

Insecure usage includes, but is not limited to: equipment for surgical implementation, atomic energy control instruments, airplane or spaceship instruments, the control or operation of dynamic, brake or safety systems designed for vehicular use, traffic signal instruments, all types of safety devices, and other applications intended to support or sustain life.

All Insecure Usage shall be made at customer's risk, and in the event that third parties lay claims to Nuvoton as a result of customer's Insecure Usage, customer shall indemnify the damages and liabilities thus incurred by Nuvoton.

*Please note that all data and specifications are subject to change without notice.
All the trademarks of products and companies mentioned in this datasheet belong to their respective owners.*