

M480 FreeRTOS LwIP TCP Client and UDP Client

Example Code Introduction for 32-bit NuMicro® Family

Information

Application	This code is an echo client that is implemented with LwIP under FreeRTOS to communicate with a server by TCP and UDP protocols.
BSP Version	M480 Series BSP CMSIS V3.04.000
Hardware	NuMaker-PFM-M487

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1 Function Description

1.1 Introduction

This code is an echo client that is implemented with LwIP under FreeRTOS. This FreeRTOS system creates two tasks that communicate with a server by TCP and UDP protocols. The echo client will get the message from the server and then send the same message back to the server.

1.2 Principle

This FreeRTOS sample code creates two tasks. One task acts as a TCP echo client, the other a UDP echo client. A TCP echo client which is implemented with LwIP. It is configured statically to 192.168.0.2:80 and gets message from IP address 192.168.0.3. A UDP echo client which is implemented with LwIP. It is configured statically to 192.168.0.2:81 and gets message from IP address 192.168.0.3. After the two tasks get the message, they will send the same message back to the server.

1.3 Demo Result

The screenshot shows a software interface with two main sections: 'TCP Option' and 'UDP Option'. In the 'TCP Option' section, the 'Server IP' is set to 192.168.0.3 and the 'Port' is 80. The 'Client' radio button is selected. In the 'UDP Option' section, the 'Target IP' is set to 192.168.0.2 and the 'Port' is 81. The 'Client' radio button is selected. Below these sections is a text input field labeled 'Edit Data(Send Data)' containing the text 'Nuvoton'. To the right of these fields is a 'Communication Data' log window. The log shows the following sequence of events:

```
TCP Communication End  
0002 R [17:08:35'457] : Nuvoton  
0001 S [17:08:35'452] : Nuvoton  
0000 R [17:08:33'773] : Hello server ?  
TCP Communication Start  
TCP Communication Start  
UDP Communication End  
0002 R [17:08:31'749] : Nuvoton  
0001 S [17:08:31'746] : Nuvoton  
0000 R [17:08:31'264] : Hello server ?  
UDP Communication Start
```

2 Code Description

Set LwIP network interface and create two tasks for TCP and UDP echo clients :

```
static void vClientTask(void *pvParameters)
{
    ip_addr_t ipaddr;
    ip_addr_t netmask;
    ip_addr_t gw;
    /*IP address setting*/
    IP4_ADDR(&gw, 192,168,0,1);
    IP4_ADDR(&ipaddr, 192,168,0,2);
    IP4_ADDR(&netmask, 255,255,255,0);
    printf("Local IP:192.168.0.3\n");

    /*network interface initial*/
    tcpip_init(NULL, NULL);
    netif_add(&netif, &ipaddr, &netmask, &gw, NULL, ethernetif_init, tcpip_input);
    netif_set_default(&netif);
    netif_set_up(&netif);

    /*EMAC interrupt enable*/
    NVIC_SetPriority(EMAC_TX_IRQn, configLIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY + 1);
    NVIC_EnableIRQ(EMAC_TX_IRQn);
    NVIC_SetPriority(EMAC_RX_IRQn, configLIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY + 1);
    NVIC_EnableIRQ(EMAC_RX_IRQn);

    tcp_echoclient_netconn_init(); /*Create TCP client task*/
    udp_echoclient_netconn_init(); /*Create UDP client task*/
    vTaskSuspend(NULL);
}
```

TCP echo client task function :

```
static void tcp_echoclient_netconn_thread(void *arg)
{
    struct netconn *conn;
    err_t err;
    ip_addr_t ipaddr;

    IP4_ADDR(&ipaddr, 192,168,0,3);
```

```
while(1) {
    conn = netconn_new(NETCONN_TCP);      /* Create a new TCP connection handle */
    if(conn!= NULL) {
        /* Bind to port 80 with default IP address */
        err = netconn_bind(conn, NULL, 80);

        if(err == ERR_OK) {
            err = netconn_connect(conn, &ipaddr, 80);      /*connect to server*/
            if(err == ERR_OK) {
                printf("Connect server succeed ! \n");
                /*Send a message to server*/
                netconn_write(conn, (const unsigned char*)"Hello server !",
                              (size_t)strlen("Hello server !"), NETCONN_NOCOPY);
                tcp_client_serve(conn);
            } else {
                printf("Connect server fail ! \n");
            }
        } else {
            printf("can not bind netconn");
        }
        netconn_delete(conn);
    } else {
        printf("can not create netconn");
    }
    vTaskDelay(50 / portTICK_RATE_MS);
}

void tcp_client_serve(struct netconn *conn)
{
    struct netbuf *inbuf;
    char* buf;
    u16_t buflen;

    while(1) {
        printf("Wait for TCP data      ...");

        /* Read the data from the port, blocking if nothing yet there.
           We assume the request is in one netbuf */
        if(netconn_recv(conn,&inbuf) != ERR_OK) {
            netbuf_delete(inbuf);
        }
    }
}
```

```
        break;
    }

    printf(" [OK] ...\\n");
    if(inbuf != NULL) {
        if(netconn_err(conn) == ERR_OK) {
            netbuf_data(inbuf, (void**)&buf, &buflen);
            netconn_write(conn, (const unsigned char*)buf, (size_t)buflen,
                          NETCONN_NOCOPY);
        }
    }

    /* Delete the buffer (netconn_recv gives us ownership,
       so we have to make sure to deallocate the buffer) */
    netbuf_delete(inbuf);
    printf(" [OK] ...\\n");
}
}
```

UDP echo client task function :

```
static void udp_echoclient_netconn_thread(void *arg)
{
.....
    IP4_ADDR(&ipaddr, 192,168,0,3);

    while(1) {
        conn = netconn_new(NETCONN_UDP);      /* Create a new UDP connection handle */
        if(conn!= NULL) {
            /* Bind to port 81 with default IP address */
            err = netconn_bind(conn, NULL, 81);

            if(err == ERR_OK) {
                err = netconn_connect(conn, &ipaddr, 81); /*connect to server*/
                if(err == ERR_OK) {
                    printf("Connect server succeed ! \\n");
                    /* Prepare data */
                    buf_send = netbuf_new();
                    payload_len = strlen("Hello server !");
                    data = netbuf_alloc(buf_send, payload_len);
                    memcpy(data, "Hello server !", payload_len);
                    /* Send the packet */
                }
            }
        }
    }
}
```

```
    netconn_sendto(conn, buf_send, &ipaddr, 81);
    /* Free the buffer */
    netbuf_delete(buf_send);

    while(1) {
        printf("Wait for UDP data ...");
        if(netconn_recv(conn, &buf) != ERR_OK) {
            break;
        }
        printf(" [OK] ...\\n");

        /* Get destination IP address and port*/
        addr = netbuf_fromaddr(buf);
        port = netbuf_fromport(buf);

        /* Get the payload and length */
        payload_len = buf->p->len;
        payload_data = buf->p->payload;

        /* Prepare data */
        buf_send = netbuf_new();
        data = netbuf_alloc(buf_send, payload_len);
        memcpy(data, payload_data, payload_len);

        /* Send the packet */
        netconn_sendto(conn, buf_send, addr, port);
        /* Free the buffer */
        netbuf_delete(buf_send);
        netbuf_delete(buf);
    }
} else {
    printf("Connect server fail ! \\n");
}
}

netconn_delete(conn);
}

vTaskDelay(50 / portTICK_RATE_MS);
}
```

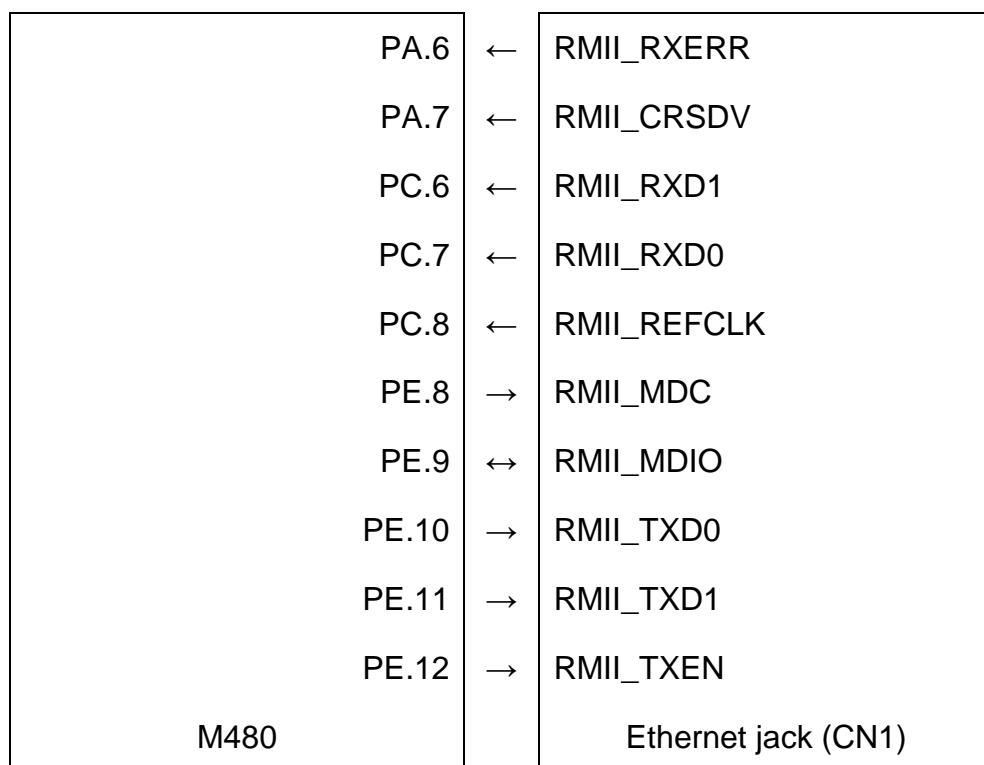
3 Software and Hardware Environment

● Software Environment

- BSP version
 - ◆ M480 Series BSP CMSIS V3.04.000
- IDE version
 - ◆ Keil uVersion 5.26

● Hardware Environment

- Circuit components
 - ◆ NuMaker-PFM-M487 v3.0
- Diagram



4 Directory Information

EC_M480_FreeRTOS_IwIP_TCP_Client_And_UDP_Client_V1.00	
Library	Sample code header and source files
CMSIS	Cortex® Microcontroller Software Interface Standard (CMSIS) by Arm® Corp.
Device	CMSIS compliant device header file
StdDriver	All peripheral driver header and source files
SampleCode	
ExampleCode	Source file of example code
ThirdParty	
FreeRTOS	A real time operating system available for free download. Its official website is: http://www.freertos.org/
IwIP	A widely used open source TCP/IP stack designed for embedded systems. Its official website is: http://savannah.nongnu.org/projects/lwip/

5 How to Execute Example Code

1. Browsing into sample code folder by Directory Information (section 4) and double click LwIP_TCP_And_UDP_Client.uvproj.
2. Enter Keil compile mode
 - a. Build
 - b. Download
 - c. Start/Stop debug session
3. Enter debug mode
 - a. Run

6 Revision History

Date	Revision	Description
Oct. 11, 2019	1.00	1. Initially issued.

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