

## NUC123 CMSIS BSP Directory

Directory Introduction for 32-bit NuMicro™ Family

### Directory Information

<b>Document</b>	Driver reference manual and reversion history.
<b>Library</b>	Driver header and source files.
<b>SampleCode</b>	Driver sample code.

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For additional information or questions, please contact: Nuvoton Technology Corporation.

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## 1 Document Information

<b>BSP Revision History</b>	Show all the revision history about specific BSP.
<b>Driver Reference Guide</b>	Describe the definition, input and output of each API.

## 2 Library Information

<b>CMSIS</b>	CMSIS definitions by ARM® Corp.
<b>Device</b>	CMSIS compliant device header file.
<b>StdDriver</b>	All peripheral driver header and source files.

### 3 Sample Code Information

<code>\SampleCode\Hard_Fault_Sample</code>	Show hard fault information when hard fault happened.
<code>\SampleCode\Template</code>	Software Development Template.
<code>\SampleCode\Semihost</code>	A sample code to show how to debug with semihost message print.
<code>\SampleCode\RegBased</code>	The sample codes which access control registers directly.
<code>\SampleCode\StdDriver</code>	NUC123 Driver Samples

## 4 \SampleCode\RegBased

<b>ADC_ContinuousScanMode</b>	Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.
<b>ADC_PwmTrigger</b>	Demonstrate how to trigger ADC by PWM.
<b>ADC_ResultMonitor</b>	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.
<b>ADC_SingleCycleScanMode</b>	Demonstrate how to use single cycle scan mode and finishes one cycle of conversion for the specified channels.
<b>ADC_SingleMode</b>	Demonstrate how to use single mode and finishes the conversion of the specified channel.
<b>CRC_8</b>	Perform CRC-8 operation and get the CRC checksum result.
<b>CRC_CCITT</b>	Perform CRC-CCITT operation and get the CRC checksum result.
<b>FMC_RW</b>	Demonstrate how to read/program embedded flash by ISP function.
<b>GPIO_EINTAndDebounce</b>	Demonstrate how to use GPIO external interrupt function and de-bounce function.
<b>GPIO_INT</b>	Demonstrate how to use GPIO interrupt function.
<b>GPIO_OutputInput</b>	Demonstrate how to set GPIO pin mode and use pin data input/output control.
<b>GPIO_PowerDown</b>	Demonstrate how to wake-up form Power-down mode by GPIO interrupt.
<b>I2C_EEPROM</b>	Demonstrate how to access EEPROM by I <sup>2</sup> C interface.
<b>I2C_GCMode_Master</b>	Demonstrate how a Master uses I <sup>2</sup> C address 0x0 to write data to I <sup>2</sup> C Slave. Needs to work with I2C_GCMode_Slave sample code.
<b>I2C_GCMode_Slave</b>	Demonstrate how to receive Master data in GC (General Call) mode. Needs to work with I2C_GCMode_Master

	sample code.
<b>I2C_Master</b>	Demonstrate how a Master access Slave. Needs to work with I2C_Slave sample code.
<b>I2C_Slave</b>	Demonstrate how to set I <sup>2</sup> C in slave mode to receive the data of a Master. Needs to work with I2C_Master sample code.
<b>I2C_Wakeup_Master</b>	Demonstrate how to wake-up MCU from power-down. Needs to work with I2C_Wakeup_Slave sample code.
<b>I2C_Wakeup_Slave</b>	Demonstrate how to set I <sup>2</sup> C to wake-up MCU from power-down mode. Needs to work with I2C_Wakeup_Master sample code.
<b>I2S_Master</b>	Demonstrate how I <sup>2</sup> S works in master mode. This sample code needs to work with I2S_Slave sample code.
<b>I2S_Slave</b>	Demonstrate how I <sup>2</sup> S works in slave mode. This sample code needs to work with I2S_Master sample code.
<b>PDMA</b>	Demonstrate how to use PDMA channel 0 to transfer data from memory to memory.
<b>PS2</b>	Demonstrate how to control PS/2 mouse movement on the screen.
<b>PWM_Capture</b>	Demonstrate how to use PWMA Channel 0 captures PWMA Channel 1 Waveform.
<b>PWM_DeadZone</b>	Demonstrate how to use PWM Dead Zone function.
<b>PWM_DoubleBuffer</b>	Use PWM Double Buffer function to change duty cycle and period of output waveform.
<b>SPI_Loopback</b>	Demonstrate SPI master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
<b>SPI_MasterDualIOMode</b>	Demonstrate how to communicate with an off-chip SPI slave device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI_SlaveDualIOMode sample code.

<b>SPI_MasterFifoMode</b>	Demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code needs to work with SPI_SlaveFifoMode sample code.
<b>SPI_SlaveDualIOMode</b>	Demonstrate how to communicate with an off-chip SPI master device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI_MasterDualIOMode sample code.
<b>SPI_SlaveFifoMode</b>	Demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code.
<b>SYS</b>	Demonstrate how to change system clock to different PLL frequency and output system clock from CLKO pin.
<b>TIMER_Capture</b>	Demonstrate how to use timer2 capture event to capture timer2 counter value.
<b>TIMER_Counter</b>	Demonstrate how to use timer1 counter input function to count the input event.
<b>TIMER_PeriodicINT</b>	Demonstrate how to perform timer counting in periodic mode.
<b>TIMER_PowerDown</b>	Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.
<b>UART_Autoflow_Master</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Slave.
<b>UART_Autoflow_Slave</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Master.
<b>UART_IrDA_Master</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Master.

<b>UART_PDMA</b>	Transmit and receive UART data with PDMA.
<b>UART_RS485_Master</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Slave.
<b>UART_RS485_Slave</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Master.
<b>UART_TxRx_Function</b>	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
<b>UART_Wakeup</b>	Show how to wake up system form Power-down mode by UART interrupt.
<b>WDT_PowerDown</b>	Demonstrate how to use WDT time-out interrupt event to wake-up system.
<b>WDT_TimeoutINT</b>	Select one WDT time-out interval period time to generate time-out interrupt event.
<b>WDT_TimeoutReset</b>	Demonstrate how to cause WDT time-out reset system event while WDT time-out reset delay period expired.
<b>WWDT_CompareINT</b>	Select one WWDT window compare value to generate window compare match interrupt event.

**5 \SampleCode\StdDriver**

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<b>SPI_SlaveDualIOMode</b>	Demonstrate how to communicate with an off-chip SPI master device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI_MasterDualIOMode sample code.
<b>SPI_SlaveFifoMode</b>	Demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code.
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<b>UART_Autoflow_Slave</b>	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Master.

<b>UART_IrDA_Master</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART_IrDA_Master.
<b>UART_PDMA</b>	Transmit and receive UART data with PDMA.
<b>UART_RS485_Master</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Slave.
<b>UART_RS485_Slave</b>	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Master.
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<b>UART_Wakeup</b>	Show how to wake up system form Power-down mode by UART interrupt.
<b>USBD_Audio_HID_NAU8822</b>	Demonstrate how to implement a USB audio class device with HID key. NAU8822 is used in this sample code to play the audio data from Host. It also supports to record data from NAU8822 to Host.
<b>USBD_Audio_HID_Transfer</b>	A composite device sample code for USB audio class with HID data transfer function.
<b>USBD_Audio_NAU8822</b>	Demonstrate how to implement a USB audio class device. NAU8822 is used in this sample code to play the audio data from Host. It also supports to record data from NAU8822 to Host.
<b>USBD_HID_Keyboard</b>	Demonstrate how to implement a USB keyboard device. It supports to use GPIO to simulate key input.
<b>USBD_HID_Mouse</b>	Demonstrate how to implement a USB mouse device. The mouse cursor will move automatically when this mouse device connecting to PC by USB.

<b>USBD_HID_Mouse2</b>	Demonstrate how to implement a USB mouse device. It use PC0 ~ PC5 to control mouse direction and mouse key. It also supports USB suspend and remote wakeup.
<b>USBD_HID_Transfer</b>	Demonstrate how to transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with USB device.
<b>USBD_HID_Transfer_and_Keyboard</b>	Demonstrate how to implement a composite device (HID Transfer and keyboard). Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with USB device.
<b>USBD_MassStorage_DataFlash</b>	Demonstrate how to implement a USB Mass-Storage. It uses embedded data flash as storage.
<b>USBD_VCOM</b>	Demonstrate how to implement a USB virtual com port device. It supports one virtual com port.

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