

M4 DSP Convolution

NuMicro[®] 32 位系列微控制器範例代碼介紹

文件資訊

代碼簡述	本範例代碼使用M4內核DSP計算捲積(Convolution)
BSP 版本	M480 Series BSP CMSIS V3.04.000
開發平台	NuMaker-PFM-M487 Ver 3.0

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1 功能介紹

1.1 簡介

展示使用 CMSIS DSP 函數庫進行捲積運算(Convolution)，用戶可以直接使用這些函式，來實現自己的數學方程式運算。程式內比較了有無使用 DSP 計算時間的差異，並計算效率提升比率。

1.2 原理

摺積又稱捲積、疊積或旋積，是通過兩個函數 $f(x)$ 和 $g(x)$ 生成第三個函數 $h(x)$ 的一種數學算子，記為 $h(x)=(f*g)(x)$ ，它是其中一個函數翻轉並平移後與另一個函數的乘積的積分，是一個對平移量的函數，也就是：

$$(f * g)(t) \stackrel{\text{def}}{=} \int f(\tau)g(t - \tau)d\tau$$

以下範例圖解其計算方法與過程：

1.有兩函數 $f(x)=\{1,2,3,4,5\}$ 與 $g(x)=\{-1,-2,-3,-4,-5\}$ ，並且 $g(x)$ 翻轉為 $g(-x)$

$f(x)$	$g(x)$
1 2 3 4 5	-1 -2 -3 -4 -5
$f(x)$	$g(-x)$
1 2 3 4 5	-5 -4 -3 -2 -1

2.平移兩函數 $f(x)$ 與 $g(-x)$ 相乘生成第三個函數 $h(x)$ ，其計算方式如下圖：

	$f(x)$	1 2 3 4 5
$g(-x)$	-5 -4 -3 -2 -1	
	$f(x)$	1 2 3 4 5
$g(-x)$	-5 -4 -3 -2 -1	
	⋮	
$f(x)$	1 2 3 4 5	
$g(-x)$	-5 -4 -3 -2 -1	

$$h(1)=f(1) \times g(1)= -1$$

$$h(2)=f(2) \times g(1)+ f(1) \times g(2)= -4$$

$$h(3)=f(3) \times g(1)+ f(2) \times g(2)+ f(1) \times g(3)= -10$$

以此類推，因此得 $h(x)=\{-1,-4,-10,-20,-35,-44,-46,-40,-25\}$

在CMSIS DSP函式庫內可以呼叫arm_conv_f32()來進行摺積運算，其定義如下表：

arm_conv_f32(float32_t *pSrcA, uint32_t srcALen, float32_t *pSrcB, uint32_t srcBLen, float32_t *pDst)		
參數：	*pSrcA	[in] 第一個函數f(x)
	srcALen	[in] f(x)函數樣本數
	*pSrcB	[in] 第二個函數g(x)
	srcBLen	[in] g(x)函數樣本數
	*pDst	計算輸出結果h(x)，其樣本數為srcALen+ srcBLen-1
回傳值：		無

1.3 執行結果

執行後會打印出以下資訊

```

+-----+
| DSP Convolution Sample Code |
+-----+

Calculating time with DSP instruction is 0.240917 ms
Calculating time without DSP instruction is 0.866167 ms
Efficiency increase rate is 3.60

```

2 代碼介紹

使用CMSIS DSP函數庫進行捲積運算：

```
/* Calculate convolution with M4 DSP instruction */
arm_conv_f32(testInput_f32_1kHz_15kHz, TEST_LENGTH_SAMPLES, firCoeffs32, NUM_TAPS,
conoutput);
```

接著使用CPU進行相同的計算：

```
/* Convolution (length of the first input vector, length of the second input vector) */
void Convolution(int n,int m)
{
    CONLOutput = TEST_LENGTH_SAMPLES + NUM_TAPS - 1;
    for(i = 0; i < CONLOutput; ++i) {
        CONoutput[i] = 0;
    }
    for(i = 0; i < n; ++i) {
        for(j = 0; j < m; ++j) {
            CONoutput[i + j] += testInput_f32_1kHz_15kHz[i] * firCoeffs32[j];
        }
    }
}
```

把計數器換成時間，其中計數器時鐘源為HXT 12MHz：

```
/* Calculate the time, timer clock source is 12M, unit is ms */
DSPCalTime = (DSPCalTime/12000000) * 1000;
CalTime = (CalTime/12000000)* 1000;
```

3 軟體與硬體環境

● 軟體環境

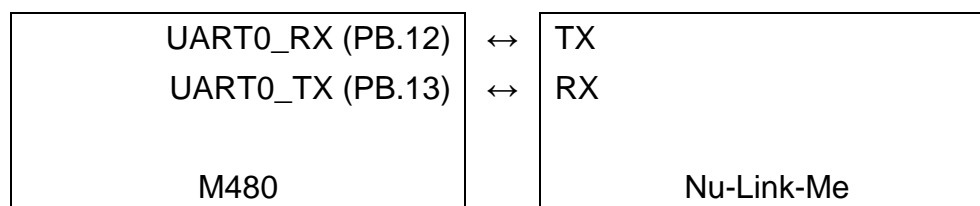
- BSP 版本
 - ◆ M480 Series BSP CMSIS V3.04.000
- IDE 版本
 - ◆ Keil uVersion 5.26

● 硬體環境

- 電路元件
 - ◆ NuMaker-PFM-M487 or other M480 Development Board
- 示意圖







M480的UART0_RX(PB.12)、UART0_TX(PB.13)連接至Nu-Link Me，打印訊息。

設置終端機的COM Port與Baud，COM Port的編號可在裝置管理員中找到「NuBridge Virtual Com Port (COMX)」，Baud設置為115200。



4 目錄資訊

EC_M480_DSP_Convolution_V1.00

 Library	Sample code header and source files
 CMSIS	Cortex [®] Microcontroller Software Interface Standard (CMSIS) by Arm [®] Corp.
 Device	CMSIS compliant device header file
 StdDriver	All peripheral driver header and source files
 SampleCode	
 ExampleCode	Source file of example code

5 如何執行範例程式

1. 根據目錄資訊章節進入 ExampleCode 路徑中的 KEIL 資料夾，雙擊 DSP_Convolution.uvproj
2. 進入編譯模式介面
 - a. 編譯
 - b. 下載代碼至記憶體
 - c. 進入 / 離開除錯模式
3. 進入除錯模式介面
 - a. 執行代碼

6 修訂紀錄

Date	Revision	Description
Jun. 21, 2019	1.00	1. 初始發布.

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